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Abstract

The Michaelis-Menten law and the Monod-Wyman-Changeux model for allosteric kinetics are derived by means of the general relaxation (decay) laws.

Michaelis-Menten law. In a classic paper [1] it was shown that the reaction

$$E + S \rightleftharpoons_{k_2}^{k_1} ES \to^{k_3} E + P \quad , \tag{1}$$

where E is an enzyme, S is a "substrate", P is a product of reaction and $k_{1,2,3}$ are reaction constants, obeys approximately the Michaelis-Menten law

$$\frac{dp}{dt} = const \frac{s}{const + s} \quad , \tag{2}$$

where s, p are the concentrations of the substrate S and, respectively, product P and t is the time. The derivation goes as follows:

$$de/dt = -k_1 e \cdot s + k_2(es) + k_3(es) ,$$

$$ds/dt = -k_1 e \cdot s + k_2(es) ,$$

$$d(es)/dt = k_1 e \cdot s - k_2(es) - k_3(es) ,$$

$$dp/dt = k_3(es) ,$$

(3)

where e and (es) are the concentration of the enzyme E and, respectively, the complex enzymesubstrate ES; from the first and the third equations (3) we get e + (es) = const, which expresses the conservation of the enzyme concentration; assuming the equilibrium $k_1 e \cdot s = k_2(es)$ (ds/dt = 0) we get $e + (k_1/k_2)e \cdot s = const$ from the conservation law, or e = const/(const + s) and $dp/dt = const \cdot s/(const + s)$ from the last equation (3); this is the Michaelis-Menten law.

It is easy to see that this derivation and the kinetic equations (3) have several drawbacks; the kinetic equations imply the law of mass action, based usually on (low-dilution, high-mobility) diffusion, which is rather unrealistic in enzymatic reactions; the final rate k_3 must be much smaller that the rate k_2 , in order to have equilibrium in the first step of the reaction; this implies a low concentration of enzyme; it would be more reasonably to write the equilibrium as $k_1e \cdot s =$

 $k_2(es) + k_3(es)$, which leads to the same Michaelis-Menten law,[2] or to admit the reversibility in the last step of the kinetic equations, *i.e.* to write the reaction as

$$E + S \rightleftharpoons_{k_2}^{k_1} ES \rightleftharpoons_{k_4}^{k_3} E + P .$$

$$\tag{4}$$

In any case, the underlying mechanism of the Michaelis-Menten law is questionable, though the law with its saturation-like character seems to be valid in practice; some versions of the law imply often an inflexion point (a sigmoid curve), which is validated by practice.

Kinetic laws. The problem consists in estimating the reaction product as a function of the concentration of one reactants, say the substrate, at equilibrium for a general reaction written as $(E, S) \rightleftharpoons (E, P)$. We denote by f the concentration of the product and by x the concentration of the substrate. Increasing x by dx will increase the product by df; the simplest law for this process is $df = B\lambda dx$, where B and λ are constants. The product disappears also, with the simplest (decaying, relaxing) law df=- λ fdx. Combining the two contributions we get the kinetic equation

$$\frac{df}{dx} + \lambda f = B\lambda \; ; \tag{5}$$

the solution is

$$f = B + Ce^{-\lambda x} , \qquad (6)$$

where C is a constant; for a vanishing product at the initial x = 0, we get B + C = 0 and

$$f = B(1 - e^{-\lambda x}) ; (7)$$

the product is generated initially with the rate $B\lambda$, as obtained either from equation (7) for small x ($f \simeq B\lambda x$) or from equation (5) by neglecting the small term λf ; and for larger x it saturates at f = B (equation (7)), *i.e.* its slope is vanishing in equation (5) which gives indeed f = B.

The processes described above can be complicated by including a cooperative aspect; instead of $df = B\lambda dx$ we may have $df = 2B\lambda x dx$ and instead of $df = -\lambda f dx$ we may have $df = -2\lambda x f dx$, leading to the equation

$$\frac{df}{dx} + 2\lambda x f = 2B\lambda x \; ; \tag{8}$$

whose solution is

$$f = B + Ce^{-\lambda x^2} , \qquad (9)$$

or

$$f = B(1 - e^{-\lambda x^2}) \tag{10}$$

for f(x = 0) = 0. This solution has an inflexion point. Similarly, we can consider the equation

$$\frac{df}{dx} + \lambda \alpha x^{\alpha - 1} f = B \lambda \alpha x^{\alpha - 1} \tag{11}$$

with $\alpha > 1$ and get a generalized solution

$$f = B(1 - e^{-\lambda x^{\alpha}}) . \tag{12}$$

Monod-Wyman-Changeux model.[3, 4] First we note that equation (7) can also be written as

$$f = B \frac{e^{\lambda x} - 1}{e^{\lambda x}} \simeq B \frac{\lambda x}{1 + \lambda x} = const \frac{x}{const + x} , \qquad (13)$$

which is the Michaelis-Menten law. Similarly, using equation (10) or equation (12), we get $f \simeq const \cdot x^2/(const + x^2)$ or $f \simeq const \cdot x^{\alpha}/(const + x^{\alpha})$, which is a generalization of the Michaelis-Menten law.

The relaxation equation (6) suggests a decaying law, which, written for two populations (two channels, allosteric activity), reads

$$N_1 = N_{01}e^{-\lambda_1 x}$$
, $N_2 = N_{02}e^{-\lambda_2 x} = N_{01}e^{-\lambda_2 x}/L$, (14)

where $L = N_{01}/N_{02}$; it is worth noting that

$$\frac{e^{\lambda_1 x}}{e^{\lambda_1 x} + Le^{\lambda_2 x}} = \frac{N_{01}/N_1}{N_{01}/N_1 + N_{01}/N_2} = \frac{N_2}{N_1 + N_2} ,$$

$$\frac{Le^{\lambda_2 x}}{e^{\lambda_1 x} + Le^{\lambda_2 x}} = \frac{N_{01}/N_2}{N_{01}/N_1 + N_{01}/N_2} = \frac{N_1}{N_1 + N_2} ,$$
(15)

so that $e^{\lambda_1 x}$ and $Le^{\lambda_2 x}$ can be used as statistical weights. We may write also

$$\frac{e^{\lambda_1 x}}{e^{\lambda_1 x} + Le^{\lambda_2 x}} \simeq \frac{(1 + \lambda_1 x/n)^n}{(1 + \lambda_1 x/n)^n + L(1 + \lambda_2 x/n)^n}$$
(16)

or, redefining $\lambda_1 x/n \to x$ and denoting $\lambda_2 = c\lambda_1$,

$$\frac{e^{\lambda_1 x}}{e^{\lambda_1 x} + Le^{\lambda_2 x}} \simeq \frac{(1 + \lambda_1 x/n)^n}{(1 + \lambda_1 x/n)^n + L(1 + \lambda_2 x/n)^n} = \frac{(1 + x)^n}{(1 + x)^n + L(1 + cx)^n} ;$$
(17)

this is the Monod-Wyman-Changeux model. We can see that $(1 + x)^n$ has the aspect of a sum of multiple states with weights 1 and x, so we can define the mean of the x-state

$$Y = \frac{\frac{x}{1+x}(1+x)^n + \frac{cx}{1+cx}L(1+cx)^n}{(1+x)^n + L(1+cx)^n} = \frac{x(1+x)^{n-1} + Lcx(1+cx)^{n-1}}{(1+x)^n + L(1+cx)^n} ,$$
(18)

which is the so-called saturation function (it exhibits saturation and inflexions). By equation (12) we may explace x by x^{α} in equation (18), which is a generalization of the saturation law.

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